

# REAL ALGEBRAIC GEOMETRY LECTURE NOTES (12 Continued: 26/11/2009)

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## THE TARSKI-SEIDENBERG PRINCIPLE

**Recall.** Let  $R$  be a real closed field,  $a \in R$ . Define

$$\text{sign}(a) := \begin{cases} 1 & \text{if } a > 0, \\ 0 & \text{if } a = 0, \\ -1 & \text{if } a < 0. \end{cases}$$

The Tarski-Seidenberg Principle is the following result.

**Theorem 1.** Let  $f_i(\underline{T}, X) = h_{i,m_i}(\underline{T})X^{m_i} + \dots + h_{i,0}(\underline{T})$  for  $i = 1, \dots, s$  be a sequence of polynomials in  $n+1$  variables ( $\underline{T} = (T_1, \dots, T_n), X$ ) with coefficients in  $\mathbb{Z}$ . Let  $\epsilon$  be a function from  $\{1, \dots, s\}$  to  $\{-1, 0, 1\}$ . Then there exists a finite boolean combination  $B(\underline{T}) := S_1(\underline{T}) \vee \dots \vee S_p(\underline{T})$  of polynomial equations and inequalities in the variables  $T_1, \dots, T_n$  with coefficients in  $\mathbb{Z}$  such that for every real closed field  $R$  and for every  $\underline{t} \in R^n$ , the system

$$\begin{cases} \text{sign}(f_1(\underline{t}, X)) = \epsilon(1) \\ \vdots \\ \text{sign}(f_s(\underline{t}, X)) = \epsilon(s) \end{cases}$$

has a solution  $x \in R$  if and only if  $B(\underline{t})$  holds true in  $R$ .

**Notation I.** Let  $f_1(X), \dots, f_s(X)$  be a sequence of polynomials in  $R[X]$ . Let  $x_1 < \dots < x_N$  be the roots in  $R$  of all  $f_i$  that are not identically zero.

Set  $x_0 := -\infty, x_{N+1} := +\infty$

**Remark 1.** Let  $m := \max(\deg f_i, i = 1, \dots, s)$ . Then  $N \leq sm$ .

Set  $I_k := ]x_k, x_{k+1}[$ ,  $k = 0, \dots, N$

**Remark 2.**  $\text{sign}(f_i(x))$  is constant on  $I_k$ , for each  $i \in 1, \dots, s$ , for each  $k \in 0, \dots, N$ .

Set  $\text{sign}(f_i(I_k)) := \text{sign}(f_i(x))$ ,  $x \in I_k$

**Notation II.** Let  $SIGN_R(f_1, \dots, f_s)$  be the matrix with  $s$  rows and  $2N + 1$  columns whose  $i^{\text{th}}$  row (for  $i = \{1, \dots, s\}$ ) is

$$\text{sign}(f_i(I_0)), \text{sign}(f_i(x_1)), \text{sign}(f_i(I_1)), \dots, \text{sign}(f_i(x_N)), \text{sign}(f_i(I_N)).$$

i.e.  $SIGN_R(f_1, \dots, f_s)$  is an  $s \times (2N + 1)$  matrix with coefficients in  $\{-1, 0, 1\}$  and

$$SIGN_R(f_1, \dots, f_s) := \begin{pmatrix} \text{sign}f_1(I_0) & \text{sign}f_1(x_1) & \dots & \text{sign}f_1(x_N) & \text{sign}f_1(I_N) \\ \text{sign}f_2(I_0) & \text{sign}f_2(x_1) & \dots & \text{sign}f_2(x_N) & \text{sign}f_2(I_N) \\ \vdots & \vdots & & \vdots & \vdots \\ \text{sign}f_s(I_0) & \text{sign}f_s(x_1) & \dots & \text{sign}f_s(x_N) & \text{sign}f_s(I_N) \end{pmatrix}$$

**Remark 3.** Let  $f_1, \dots, f_s \in R[X]$  and  $\epsilon : \{1, \dots, s\} \rightarrow \{-1, 0, +1\}$ . The system

$$\begin{cases} \text{sign}(f_1(X)) = \epsilon(1) \\ \vdots \\ \text{sign}(f_s(X)) = \epsilon(s) \end{cases}$$

has a solution  $x \in R$  if and only if one column of  $SIGN_R(f_1, \dots, f_s)$  is precisely

the matrix  $\begin{bmatrix} \epsilon(1) \\ \vdots \\ \epsilon(s) \end{bmatrix}$ .

**Notation III.** Let  $M_{P \times Q} :=$  the set of  $P \times Q$  matrices with coefficients in  $\{-1, 0, +1\}$ .

Set  $W_{s,m} :=$  the disjoint union of  $M_{s \times (2l+1)}$ , for  $l = 0, \dots, sm$ .

**Notation IV.** Let  $\epsilon : \{1, \dots, s\} \rightarrow \{-1, 0, 1\}$ . Set

$$W(\epsilon) = \left\{ M \in W_{s,m} : \text{one column of } M \text{ is } \begin{bmatrix} \epsilon(1) \\ \vdots \\ \epsilon(s) \end{bmatrix} \right\} \subseteq W_{s,m}$$

**Lemma 2.** (Reformulation of remark 3 using notation IV) Let  $\epsilon : \{1, \dots, s\} \rightarrow \{-1, 0, +1\}$ ,  $R$  real closed field and  $f_1(X), \dots, f_s(X) \in R[X]$  of degree  $\leq m$ . Then the system

$$\begin{cases} \text{sign}(f_1(X)) = \epsilon(1) \\ \vdots \\ \text{sign}(f_s(X)) = \epsilon(s) \end{cases}$$

has a solution  $x \in R$  if and only if  $SIGN_R(f_1, \dots, f_s) \in W(\epsilon)$ .

By lemma 2, we see that the proof of the Tarski Transfer (theorem 1) reduces to showing the following proposition:

**(Main) Proposition 3.** Let  $f_i(\underline{T}, X) := h_{i,m_i}(\underline{T})X^{m_i} + \dots + h_{i,0}(\underline{T})$  for  $i = 1, \dots, s$  be a sequence of polynomials in  $n+1$  variables with coefficients in  $\mathbb{Z}$ , and let  $m := \max\{m_i | i = 1, \dots, s\}$ . Let  $W'$  be a subset of  $W_{s,m}$ . Then there exists a boolean combination  $B(\underline{T}) = S_1(\underline{T}) \vee \dots \vee S_p(\underline{T})$  of polynomial equations and inequalities in the variables  $\underline{T}$  with coefficients in  $\mathbb{Z}$ , such that, for every real closed field  $R$  and every  $\underline{t} \in R^n$ , we have

$$SIGN_R(f_1(\underline{t}, X), \dots, f_s(\underline{t}, X)) \in W' \Leftrightarrow B(\underline{t}) \text{ holds true in } R.$$

**Proof.** The proof will follow by induction from the next main lemma, where we will show that  $SIGN_R(f_1, \dots, f_s)$  is completely determined by the " $SIGN_R$ " of a (possibly) longer but simpler sequence of polynomials, i.e.

$SIGN_R(f_1, \dots, f_{s-1}, f'_s, g_1, \dots, g_s)$ , where  $f'_s$  is the derivative of  $f_s$ , and  $g_1, \dots, g_s$  are the remainders of the euclidean division of  $f_s$  by  $f_1, \dots, f_{s-1}, f'_s$ , respectively.

First we will state and prove the lemma and then prove the proposition.